

Formelsammlung

1. Mechanik

$$m\ddot{\vec{r}} = \vec{F} = \frac{d\vec{p}}{dt} \quad \vec{F}_{ij} = -\vec{F}_{ji} \quad \vec{F} = -\vec{\nabla} V$$

$$V = - \int_{\vec{0}}^{\vec{r}} d\vec{r}' \cdot \vec{F}(\vec{r}') \quad W = \int_C d\vec{r} \cdot \vec{F}(\vec{r}) \quad \frac{\partial W}{\partial t} = \vec{F} \cdot \vec{v}$$

$$L = T - V \quad \frac{d}{dt} \frac{\partial L}{\partial \dot{q}_j} - \frac{\partial L}{\partial q_j} = 0 \quad \text{für } j = 1, \dots, s$$

$$p_i = \frac{\partial L}{\partial \dot{q}_i} \quad H = T + V = \sum_{i=1}^s p_i \dot{q}_i - L \quad \dot{p}_i = -\frac{\partial H}{\partial q_i} \quad \dot{q}_i = \frac{\partial H}{\partial p_i}$$

$$\{F_1, F_2\} = \sum_{i=1}^s \left(\frac{\partial F_1}{\partial q_i} \frac{\partial F_2}{\partial p_i} - \frac{\partial F_1}{\partial p_i} \frac{\partial F_2}{\partial q_i} \right) \quad \{q_j, H\} = \frac{\partial H}{\partial p_j} \quad \{p_j, H\} = -\frac{\partial H}{\partial q_j}$$

$$L = \frac{1}{2} (\dot{\xi}^T \underline{M} \dot{\xi} - \xi^T \underline{K} \xi) \quad \det(\underline{K} - \omega^2 \underline{M}) = 0$$

$$\underline{M}_{ij} = \left. \frac{\partial^2 T}{\partial \dot{q}_i \partial \dot{q}_j} \right|_{\vec{q}=\vec{q}_0} \quad \underline{K}_{ij} = \left. \frac{\partial^2 V}{\partial q_i \partial q_j} \right|_{\vec{q}=\vec{q}_0}$$

$$\sum_{j=1}^s (\underline{M}_{ij} \ddot{\xi}_j + \underline{K}_{ij} \xi_j) = 0 \quad \ddot{\eta}_\alpha + \omega_\alpha^2 \eta_\alpha = 0$$

$$\begin{aligned} p_i &= \frac{\partial F_1(q, Q)}{\partial q_i} & P_i &= -\frac{\partial F_1(q, Q)}{\partial Q_i} & p_i &= \frac{\partial F_2(q, P)}{\partial q_i} & Q_i &= \frac{\partial F_2(q, P)}{\partial P_i} \\ q_i &= -\frac{\partial F_3(p, Q)}{\partial p_i} & P_i &= -\frac{\partial F_3(p, Q)}{\partial Q_i} & q_i &= -\frac{\partial F_4(p, P)}{\partial p_i} & Q_i &= \frac{\partial F_4(p, P)}{\partial P_i} \end{aligned}$$

$$H(P, Q, t) = H(p, q, t) + \frac{\partial F_i}{\partial t} \quad \text{für } i = 1..4$$

$$H \left(q_1, \dots, q_s, \frac{\partial F_2}{\partial q_1}, \dots, \frac{\partial F_2}{\partial q_s}, t \right) + \frac{\partial F_2}{\partial t} = 0$$

2. Elektrodynamik

$$\begin{aligned}\vec{\nabla} \cdot \vec{D} &= \rho & \vec{\nabla} \times \vec{E} &= -\frac{\partial}{\partial t} \vec{B} \\ \vec{\nabla} \cdot \vec{B} &= 0 & \vec{\nabla} \times \vec{H} &= \vec{j} + \frac{\partial}{\partial t} \vec{D}\end{aligned}$$

$$\vec{D} = \epsilon_0 \epsilon_r \vec{E} \qquad \vec{B} = \mu_0 \mu_r \vec{H}$$

$$\begin{aligned}\int_{\partial V} d\vec{f} \cdot \vec{D} &= Q & \oint_{\partial F} d\vec{s} \cdot \vec{E} &= -\frac{\partial}{\partial t} \int_F d\vec{f} \cdot \vec{B} \\ \int_{\partial V} d\vec{f} \cdot \vec{B} &= 0 & \oint_{\partial F} d\vec{s} \cdot \vec{H} &= I + \frac{\partial}{\partial t} \int_F d\vec{f} \cdot \vec{D} \\ Q &= \sigma F\end{aligned}$$

$$\begin{aligned}\vec{B}(\vec{r}) &= \frac{\mu_0}{4\pi} \int d^3 r' \vec{j}(\vec{r}') \times \frac{\vec{r} - \vec{r}'}{|\vec{r} - \vec{r}'|^3} \\ \frac{\partial \rho}{\partial t} + \vec{\nabla} \cdot \vec{j} &= 0\end{aligned}$$

$$\vec{p} = \int d^3 r \vec{r} \rho(\vec{r}) \qquad \vec{m} = \frac{1}{2} \int d^3 r \vec{r} \times \vec{j}(\vec{r})$$

$$Q_{ij} = \int d^3 r \rho(\vec{r}) (3x_i x_j - r^2 \delta_{ij}) \qquad q_{\ell m} = \int d^3 r r^\ell Y_\ell^m(\theta, \varphi) \rho(\vec{r})$$

$$Y_\ell^m(\theta, \varphi) = \sqrt{\frac{2\ell+1}{4\pi} \frac{(\ell-m)!}{(\ell+m)!}} P_\ell^m(\cos\theta) e^{im\varphi} \qquad P_\ell^m(x) = (-1)^m (1-x^2)^{\frac{m}{2}} \frac{\partial^m}{\partial x^m} P_\ell(x)$$

$$P_0(x) = 1 \qquad P_1(x) = x \qquad P_2(x) = \frac{1}{2}(3x^2 - 1)$$

$$\begin{aligned}\vec{n} \cdot (\vec{D}_2 - \vec{D}_1) &= \sigma & \vec{n} \cdot (\vec{B}_2 - \vec{B}_1) &= 0 \\ (\vec{t} \times \vec{n}) \cdot (\vec{E}_2 - \vec{E}_1) &= 0 & (\vec{t} \times \vec{n}) \cdot (\vec{H}_2 - \vec{H}_1) &= \vec{t} \cdot \vec{j}_F\end{aligned}$$

$$\frac{\partial}{\partial t} (W_{mech} + W_{Feld}) = \int_V (\vec{j} \cdot \vec{E} + \frac{\partial w}{\partial t}) = - \int_V d^3 r \vec{\nabla} \cdot \vec{S} = - \int_{\partial V} d\vec{f} \cdot \vec{S}$$

$$\frac{\partial}{\partial t} (\vec{p}_{mech} + \vec{p}_{Feld})_i = \int d^3 r \left([\rho \vec{E} + \vec{j} \times \vec{B}] + \vec{D} \times \vec{B} \right)_i = \int_{\partial V} d\vec{f} \sum_{k=1}^3 n_k T_{ik}$$

$$w = \frac{1}{2} (\vec{E} \cdot \vec{D} + \vec{B} \cdot \vec{H}) \qquad \vec{S} = \vec{E} \times \vec{H}$$

$$T_{ik} = \left(\epsilon_0 \epsilon_r E_i E_k + \frac{1}{\mu_0 \mu_r} B_i B_k - \frac{1}{2} (\epsilon_0 \epsilon_r \vec{E}^2 + \frac{1}{\mu_0 \mu_r} \vec{B}^2) \delta_{ik} \right)$$

$$\vec{A}(t) = \vec{A}_0 e^{i\omega t}, \quad \vec{B}(t) = \vec{B}_0 e^{i\omega t} \quad \Rightarrow \quad \begin{aligned} \overline{\operatorname{Re} \vec{A}(t) \operatorname{Re} \vec{B}(t)} &= \frac{1}{2} \operatorname{Re}(\vec{A}_0 \vec{B}_0^*) \\ \overline{\operatorname{Re} \vec{A}(t) \times \operatorname{Re} \vec{B}(t)} &= \frac{1}{2} \operatorname{Re}(\vec{A}_0 \times \vec{B}_0^*) \end{aligned}$$

$$u = \frac{1}{\sqrt{\epsilon_r \epsilon_0 \mu_r \mu_0}} = \frac{c}{\sqrt{\epsilon_r \mu_r}} = \frac{c}{n}$$

$$\frac{\sin \vartheta_1}{\sin \vartheta_2} = \frac{k_2}{k_1} = \frac{n_2}{n_1}$$

$$\begin{aligned} \left(\frac{E_{02}}{E_{01}} \right)_{\perp} &= \frac{2n_1 \cos \vartheta_1}{n_1 \cos \vartheta_1 + n_2 \cos \vartheta_2}, & \left(\frac{E_{01r}}{E_{01}} \right)_{\perp} &= \frac{n_1 \cos \vartheta_1 - n_2 \cos \vartheta_2}{n_1 \cos \vartheta_1 + n_2 \cos \vartheta_2} \\ \left(\frac{E_{02}}{E_{01}} \right)_{\parallel} &= \frac{2n_1 \cos \vartheta_1}{n_2 \cos \vartheta_1 + n_1 \cos \vartheta_2}, & \left(\frac{E_{01r}}{E_{01}} \right)_{\parallel} &= \frac{n_2 \cos \vartheta_1 - n_1 \cos \vartheta_2}{n_2 \cos \vartheta_1 + n_1 \cos \vartheta_2} \end{aligned}$$

$$G_0^{\text{ret}}(\vec{r} - \vec{r}', t - t') = \frac{1}{4\pi |\vec{r} - \vec{r}'|} \delta(t_{\text{ret}} - t') \quad \text{mit} \quad t_{\text{ret}} = t - \frac{|\vec{r} - \vec{r}'|}{u}$$

$$\begin{aligned} \varphi(\vec{r}, t) &= \frac{1}{4\pi \epsilon_0 \epsilon_r} \int d^3 r' \frac{\rho(\vec{r}', t_{\text{ret}})}{|\vec{r} - \vec{r}'|} \\ \vec{A}(\vec{r}, t) &= \frac{\mu_0 \mu_r}{4\pi} \int d^3 r' \frac{\vec{j}(\vec{r}', t_{\text{ret}})}{|\vec{r} - \vec{r}'|} \end{aligned}$$

3. Allgemeine mathematische Formeln

$$\begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} r \sin \theta \cos \varphi \\ r \sin \theta \sin \varphi \\ r \cos \theta \end{pmatrix} \quad \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} \rho \cos \varphi \\ \rho \sin \varphi \\ z \end{pmatrix} \quad \dot{\vec{r}} = \dot{r}\vec{e}_r + r\dot{\theta}\vec{e}_\theta + r \sin \theta \dot{\varphi}\vec{e}_\varphi$$

$$f(r) = f(0) + \sum_n \frac{d^n f(r)}{dr^n} \Big|_{r=0} \frac{r^n}{n!}$$

$$\int_0^{2\pi} dx \sin^2 x = \int_0^{2\pi} dx \cos^2 x = \pi \quad \int_0^{2\pi} dx \sin x \cos x = 0$$

$$\int dx \frac{1}{\sqrt{x^2 + a^2}} = \ln(x + \sqrt{x^2 + a^2}) + C \quad \int dx \frac{1}{(x^2 + a^2)^{3/2}} = \frac{x}{a^2 \sqrt{x^2 + a^2}} + C$$

$$\int dx \frac{x^3}{(x^2 + a^2)^{3/2}} = \frac{x^2 + 2a^2}{\sqrt{x^2 + a^2}} + C \quad \int dx \frac{1}{x} = \ln|x| + C$$

$$\int_a^\infty dx \frac{b}{x\sqrt{x^2 - b^2}} = \arcsin\left(\frac{b}{x}\right) \quad \text{falls } a > b > 0$$

$$\vec{a} \times (\vec{b} \times \vec{c}) = (\vec{a} \cdot \vec{c}) \cdot \vec{b} - (\vec{a} \cdot \vec{b}) \cdot \vec{c}$$

$$\int_F d\vec{f} \cdot (\vec{\nabla} \times \vec{A}) = \oint_{\partial F} d\vec{s} \cdot \vec{A} \quad \int_V d^3r \vec{\nabla} \cdot \vec{A} = \int_{\partial V} d\vec{f} \cdot \vec{A}$$

$$\vec{\nabla} f = \frac{\partial f}{\partial \rho} \vec{e}_\rho + \frac{1}{\rho} \frac{\partial f}{\partial \varphi} \vec{e}_\varphi + \frac{\partial f}{\partial z} \vec{e}_z$$

$$\vec{\nabla} \cdot \vec{F} = \frac{1}{\rho} \frac{\partial}{\partial \rho} (\rho F_\rho) + \frac{1}{\rho} \frac{\partial}{\partial \varphi} F_\varphi + \frac{\partial}{\partial z} F_z$$

$$\vec{\nabla} \times \vec{F} = \left(\frac{1}{\rho} \frac{\partial}{\partial \varphi} F_z - \frac{\partial}{\partial z} F_\varphi \right) \vec{e}_\rho + \left(\frac{\partial}{\partial z} F_\rho - \frac{\partial}{\partial \rho} F_z \right) \vec{e}_\varphi + \left(\frac{1}{\rho} \frac{\partial}{\partial \rho} (\rho F_\varphi) - \frac{1}{\rho} \frac{\partial}{\partial \varphi} F_\rho \right) \vec{e}_z$$

$$\Delta f = \frac{\partial^2 f}{\partial \rho^2} + \frac{1}{\rho} \frac{\partial f}{\partial \rho} + \frac{1}{\rho^2} \frac{\partial^2 f}{\partial \varphi^2} + \frac{\partial^2 f}{\partial z^2}$$

$$\vec{\nabla} f = \frac{\partial f}{\partial r} \vec{e}_r + \frac{1}{r} \frac{\partial f}{\partial \theta} \vec{e}_\theta + \frac{1}{r \sin \theta} \frac{\partial f}{\partial \varphi} \vec{e}_\varphi$$

$$\vec{\nabla} \cdot \vec{F} = \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 F_r) + \frac{1}{r \sin \theta} \frac{\partial}{\partial \theta} (\sin \theta F_\theta) + \frac{1}{r \sin \theta} \frac{\partial}{\partial \varphi} F_\varphi$$

$$\begin{aligned} \vec{\nabla} \times \vec{F} &= \frac{1}{r \sin \theta} \left(\frac{\partial}{\partial \theta} (\sin \theta F_\varphi) - \frac{\partial}{\partial \varphi} F_\theta \right) \vec{e}_r + \frac{1}{r} \left(\frac{1}{\sin \theta} \frac{\partial}{\partial \rho} F_r - \frac{\partial}{\partial r} (r F_\varphi) \right) \vec{e}_\theta \\ &\quad + \frac{1}{r} \left(\frac{\partial}{\partial r} (r F_\theta) - \frac{\partial}{\partial \theta} F_r \right) \vec{e}_\varphi \end{aligned}$$

$$\Delta f = \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 \frac{\partial f}{\partial r}) + \frac{1}{r^2 \sin \theta} \frac{\partial}{\partial \theta} (\sin \theta \frac{\partial f}{\partial \theta}) + \frac{1}{r^2 \sin^2 \theta} \frac{\partial^2 f}{\partial \varphi^2}$$